



Advances and Gaps in Black Sea / Mediterranean Sea Oceanography, Sochi, December 1-3, 2014

## From Tsunami Early Detection and Warning to Multi Hazards Early Detection and Warning

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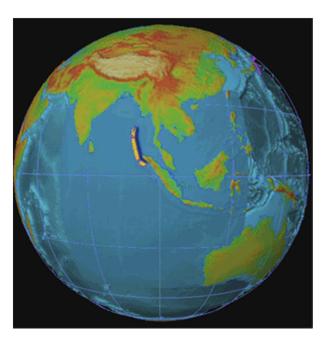


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## <u>Introduction</u>

Following the disaster induced by the Indian Ocean earthquake and tsunami on 26/12/2004, in November 2005, an Intergovernmental Coordination Group (consisting of national delegates of IOC/UNESCO member states) decided to establish the Tsunami Early Warning and Mitigation System in the North-eastern Atlantic, the Mediterranean and connected seas (ICG/NEAMTWS). Not every earthquake generates



a tsunami, but only some of them. Hence, even if an EQ event is detected and characterized in a few minutes, the generation of tsunami waves must be confirmed by monitoring of sea level in real time (recommended 15" sampling rate, data sent every 1') or by additional means

Presently NEAMTWS consists of NEAM seismic and sea level monitoring and RT data sharing and the activities of its managing bodies.





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# ICG/NEAMTWS UPDATED STRUCTURE







## Advances and Gaps to be filled

## **Advances:**

- The NEAMTWS is Operational since 2012 and Improving Further

## Gaps:

- The tsunami models know to model only the 1st wave of 3-7 waves, in spite that only sometimes the highest is the first wave, because the tsunami generation by tectonic rupture is yet not well understood.
- NEAMTWS does not cover landslide or volcano induced tsunamis
- NEAMTWS does not cover meteo-tsunamis
- NEAMTWS does not deal with flooding by storm surge\wave storms
- NEAMTWS needs additional real time sea level stations
- NEAMTWS needs quality controlled sea level data
- NEAMTWS needs data provision via GTS
- There is a need for quick detection and warning for all above events

**To fill the gaps** - a multi hazards early detection and warning system will to be proposed later in the presentation







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#### CIESM HAS BEEN SUPPORTING NEAMTWS DEVELOPMENT FROM THE BEGINNING



Contributions of the Intl. Mediterranean Science Commission (CIESM) to a Tsunami Warning System in the Mediterranean and Black Seas

by

Dr Frederic Briand, Director General, CIESM

www.ciesm.org

Presented by Dov S. Rosen, Coordinator, MedGLOSS



International Coordination Group for the Tsunami Early Warning and Mitigation System in the North Eastern Atlantic, the Mediterranean and Connected Seas (ICG/NEAMTWS)

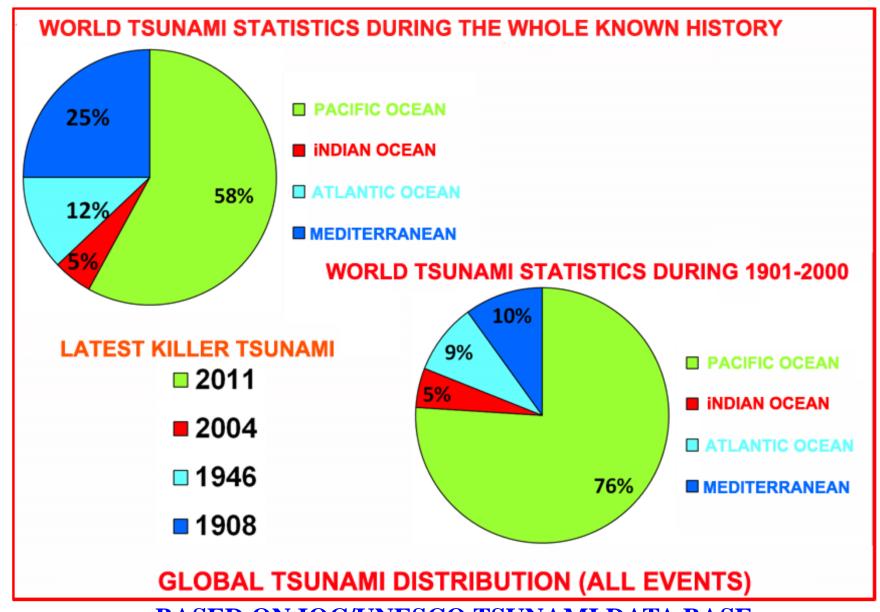
First Session (ICG-I), Palazzo Taverna, Rome, ITALY, 21-22 November 2005







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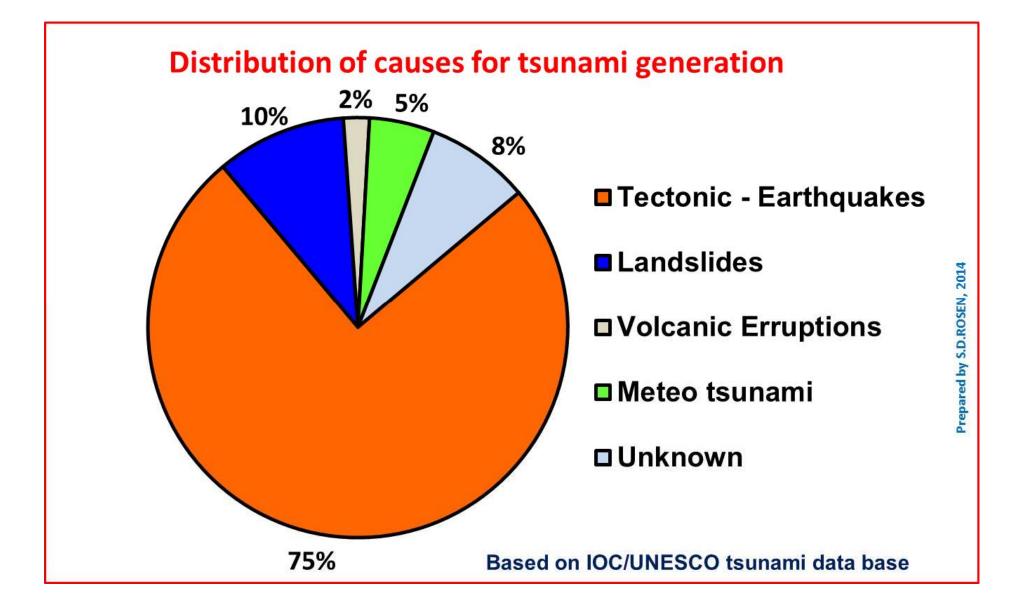


**BASED ON IOC/UNESCO TSUNAMI DATA BASE** 





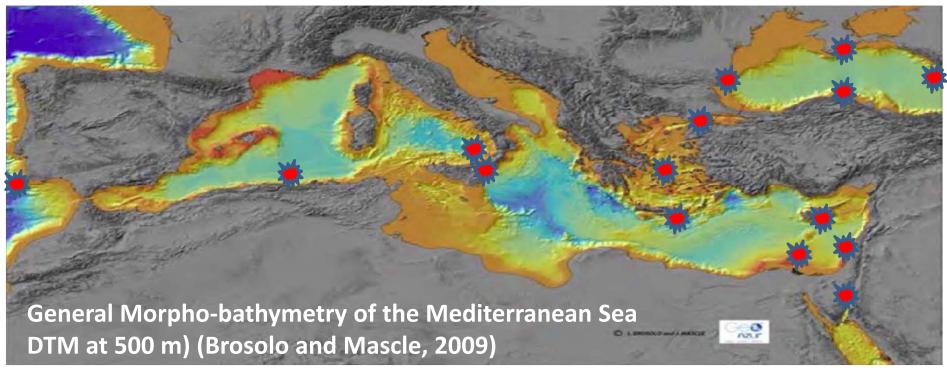
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# Potential places for generation of tsunamis in EM (Adapted after Brosolo and Mascle, 2009)



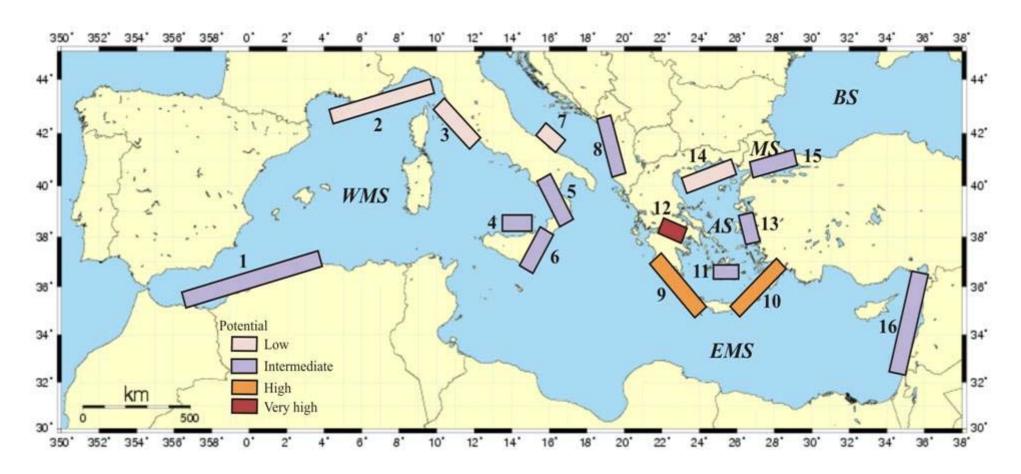
## Location of tsunamigenic areas







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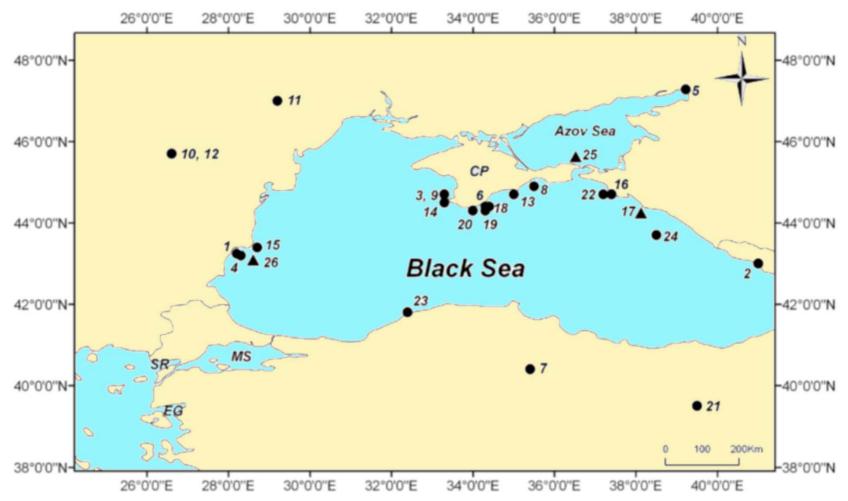
Past tsunami events areas (numbers) and their tsunami risk (colors) (From Papadopoulos, 2005)





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## Sources of tsunami generation in the Black Sea & the Azov Sea



Key: a solid circle is a seismic source, a solid triangle is a gravitative sliding source; **CP = Caspian Peninsula, EG = Edremit Gulf, MS= Marmara Sea, SR = Saros Bay. Source:** G. A. Papadopoulos et al., 2011. Tsunamis in the Black Sea,







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Sources of tsunami generation in Black Sea (Sahin, 2013)







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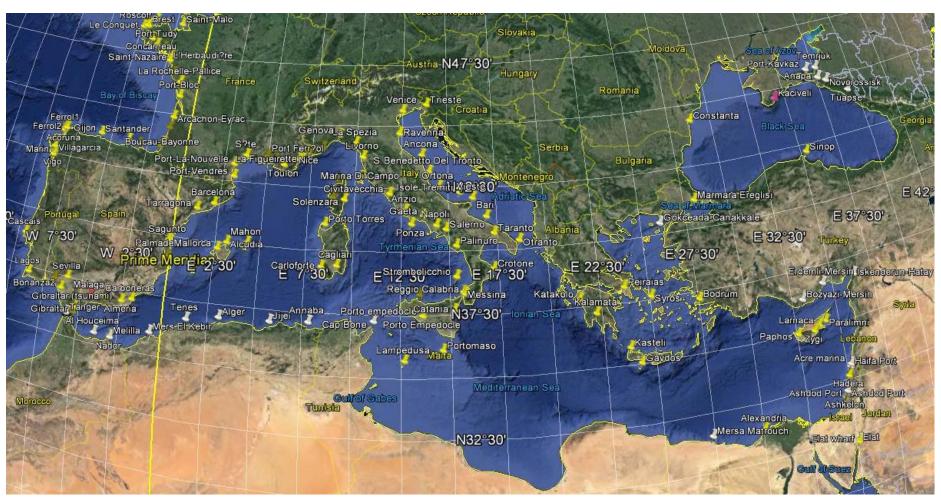






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## **Map of NEAMTWS Active Real Time Sea Level Stations** and of Potential Additional Sea Level Stations



**Legend**: Yellow - Real Time Operational Station; Red - Real Time Not Working; White - Potential Existing Sea Level Station for Upgrading to Real Time





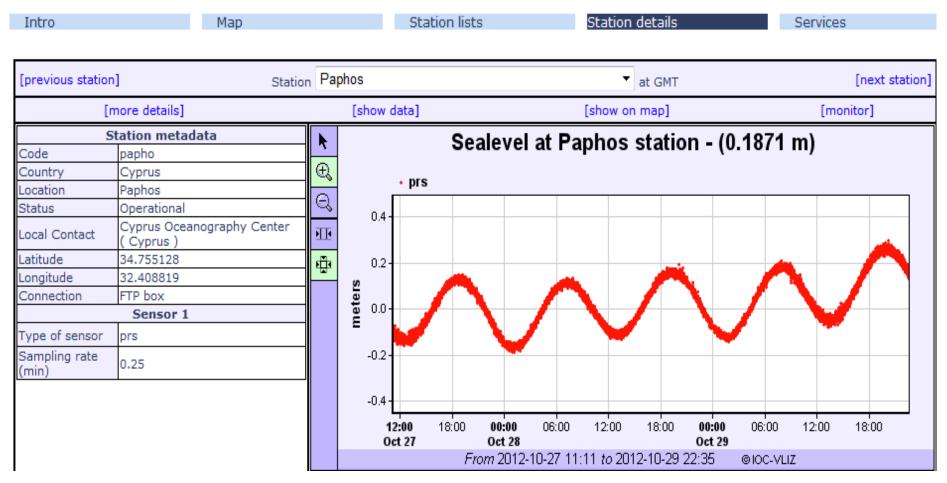


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## **Example of Real Time sea level data monitoring for NEAMTWS**

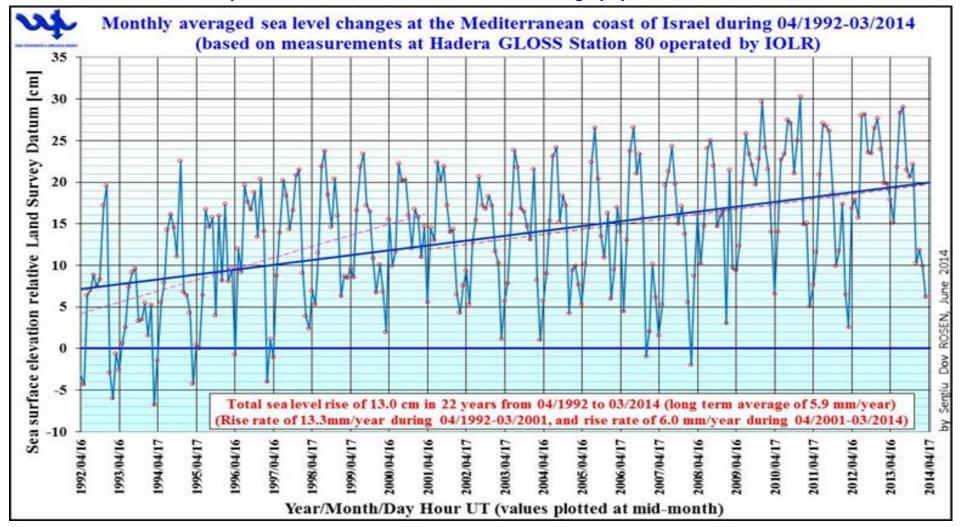


### SEA LEVEL STATION MONITORING FACILITY





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Increased sea level rise in the South Eastern Mediterranean relative to present global average rate (~3mm/year) due at least partly by the increased salinity in the area by the increased Suez Canal salty flow

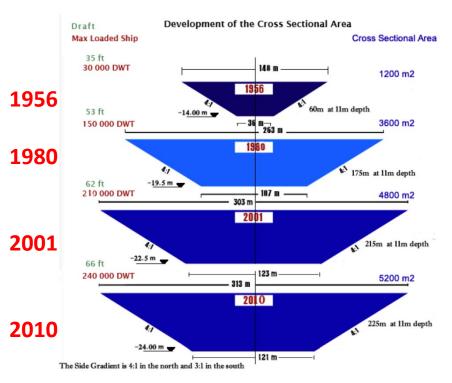




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## Change of the wet cross section of Suez Canal in time (1989-2010)

ITEM	UNIT	1869	1956	1962	1980	1994	1996	2001		2010
Percentage increase									1869-2001	
WIDTH AT 11M DEPTH	М	44	60	90	160	210	210	210	477%	
MAX DRAFT OF SHIPS	FEET	22	35	38	53	56	58	62	282%	
OVERALL LENGTH	KM	164	175	175	190.25	190.25	190.25	190.25	116%	
DOUBLED PARTS	KM	-	29	29	78	78	78	78	269%	
WATER DEPTH	М	10	14	15.5	19.5	20.5	21	22.5	225%	24
CROSS SECTIONAL AREA	M2	304	1100	1800	3600	4300	4500	4800	1579%	5208
MAX. TONNAGE (DWT)	TON	5000	30,000	80,000	150,000	180,000	185,000	210,000	4200%	



The increased saltier water flow (saltier than both the Red Sea and Mediterranean Sea) into the Mediterranean Sea at Suez Canal is estimated to be sinking to the sea bottom of the Nile delta cone, consisting unconsolidated fine sediments and with time scour into its toe, increasing the sediment deposit instability, eventually leading to a landslide and tsunami or, in case of a strong earthquake at the Hellenic Arc but deeper than 100 km (not tsunamigenic) its seismic waves may be strengthened at the Nile cone and trigger landslide and tsunami, even before sufficient toe scour would occur.



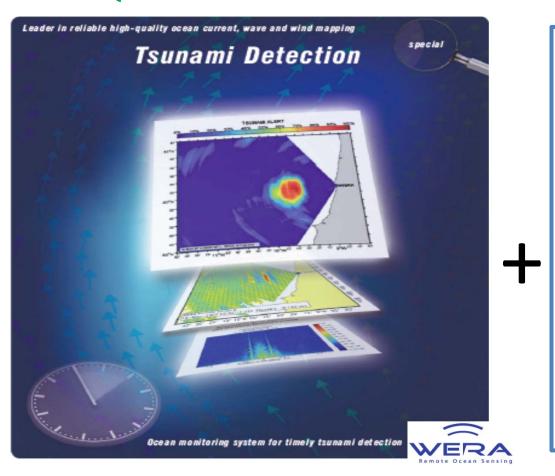




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#### FILING PART OF THE GAP: A MULTI HAZARD EARLLY WARNING SYSTEM

#### HIGH FREQUENCY RADAR STATIONS NETWORK



Densifying and
Upgrading
of Sea Level
Monitoring
Stations
to Real Time
Data Transmission
via GTS

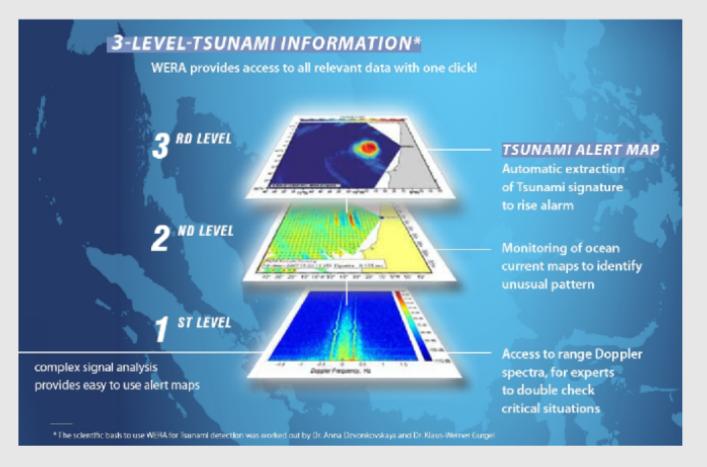






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WERA combines all information for modern Coastal Management; measurements with high spatial and temporal resolution of Surface Currents, Wind Direction and Wave Parameters and provides access to all relevant data with one click!



WERA can be fully integrated into a national Tsunami Early Warning System providing valuable data to reduce the false alarm rate improving the reliability of the entire system. For timely Tsunami detection, the shelf edge should be located > 50 km off the coast.

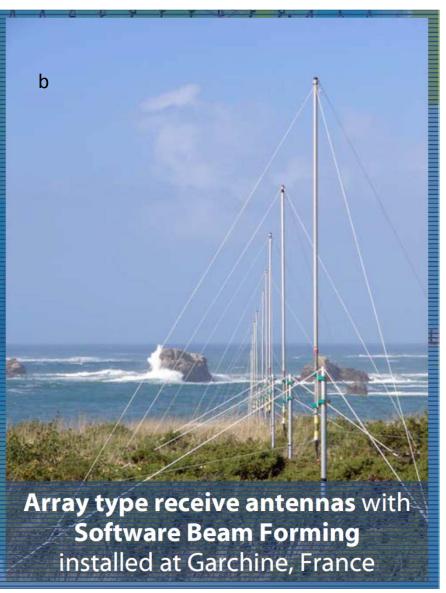






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WERA HF radar transmit (a) and receive (b) antennas



## CIESM

#### **CIESM International Scientific Forum 2014**



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## **Conclusion and Recommendation:**

An early warning system from landslide tsunamis is needed for the regions with landslide tsunamigenic potential, which must be able to detect landslide tsunamis as soon as possible after occurrence.

To fill the existing gaps in knowledge and early warning for all tsunami and other marine hazards it is proposed to develop a Multi Hazard Early Detection System consisting of:

- a. A network of array high frequency radars (WERA),
- b. Densifying of the Real Time sea level gauges network,
- c. A few complementary DARTs and/or GPS tsunami buoys.







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